tresented: ENC, Orlando, March 39

System theoretic aspects of NMR spectroscopy

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1 Introduction

System theory (see e.g. [2]) has played a major role over the past decades in many fields such as engineering. Powerful techniques which have been developed in system theory have been applied successfully to a large array of problems. Here we show how NMR spectroscopy can also be described in the language of system theory. System theoretic methods are used to address a number of problems in NMR spectroscopy. We discuss results that describe characterizations of possible NMR spectra given a fixed quantum mechanical system. In addition, we discuss the processing of NMR data and in particular new parameter estimation methods.

2 Master System

2.1 Schrödinger equation, restricted to spin dynamics

$$\dot{\psi} = -i(H_1 + \sum_{i=1}^{2} H_{2,j}u_j(t))\psi$$

- \bullet H_1 is Hamiltonian corresponding to strong magnetic field.
- $H_{2,j}$ is Hamiltonians corresponding to time-varying magnetic field (inputs).
- H₁, H₂ hermitian.
- \bullet u_1 , u_2 inputs, i.e. the excitation pulses.
- 2.2 Density matrix description (Master system)

$$\dot{\sigma}(t) = -i[H_1,\sigma(t)] - i\sum_{j=1}^k u_j(t)[H_{2,j},\sigma(t)] - \hat{R}[\sigma(t) - \sigma_{\rm eq}],$$

$$y(t) = trace(M\sigma(t)), \quad t \ge t_0$$

- · u measured output (induced magnetization).
- R relaxation superoperator.
- M measurement operator.
- σ_{eq} equilibrium density matrix.

3 Bilinear system

 $\bullet \ e(t) = vec(\sigma(t)) - vec(\sigma_{eq}), \quad t \ge 0.$

 $\bullet \ A = -i(I \otimes H_1 - H_1^T \otimes I) - R.$

 $\bullet\; N_j:=-i(I\otimes H_{2,j}-H_{2,j}^T\otimes I),\quad j=1,2.$

 $\bullet \ b_j := N_j vec(\sigma_{eq}), \quad j=1,2.$

 $c = (vec(M^T))^T.$

Under mild assumptions the master system is equivalent to the bilinear system ([7])

$$\dot{e}(t) = Ae(t) + (\sum_{j=1}^{2} u_{j}(t)N_{j})e(t) + \sum_{j=1}^{2} b_{j}u_{j}(t),$$

$$y(t) = ce(t)$$

· Bilinear systems are extensively studied in systems and control theory (see e.g. [9]).

4 One-Dimensional Experiments

$$Real(c(i\omega - A)^{-1}e_0),$$

where e_0 is the state of the system at the time when detection

5 Two-Dimensional Experiments

· 2-dimensional time signal

 $s(t_1, t_2), t_1 \ge 0, t_2 \ge 0$

• 2-dimensional Fourier transform is (special case) ([7])

$$G(\omega_1,\omega_2) = c(i\omega_1 I - A)^{-1} T_3 (i\omega_2 I - A)^{-1} e_0$$

- $-e_0$ is the state at the end of the preparation period.
- T3 is a matrix 'associated' with the mixing period.

6 Classification of 1-D experiments

Addition schemes (e.g. phase cycling):

- Several different (single scan) experiments are run.
- The resulting measurements (fids) are added.

Theorem 8.1 ([8]) The set of all one-dimensional spectra obtainable using addition schemes is given by

$$\{c(i\omega-A)^{-1}e_0\mid e_0\in\mathcal{E}\},$$

where E is the smallest subspace of \mathbb{C}^n that 1. contains b1 and b2

2. and is invariant under A, N1 and N2.

7 Classification of 2-D experiments

Addition schemes (e.g. phase cycling):

- Several different (single scan) experiments are run
- The resulting measurements (fids) are added.
- Resulting spectrum

Freedom g spectrum
$$G(\omega_1, \omega_2)$$

$$= c(i\omega_1 I - A)^{-1} \left(\sum_{i=1}^{k_2} \lambda_j T_{3,j} \right) (i\omega_2 I - A)^{-1} \left(\sum_{i=1}^{k_1} \mu_j e_{1,i} \right).$$

Theorem 7.1 ([8]) The set of all two-dimens tainable using addition schemes is given by

$$\{c(i\omega_1-A)^{-1}T_3(i\omega_2I-A)^{-1}e_0\mid T_3\in\mathcal{T}, e_0\in\mathcal{E}\},\$$

1. E is the smallest subspace of Cn that

(a) contains b_1 and b_2 (b) and is invariant under A, N1 and N2.

2. T is the matrix algebra generated by A, N_1 and N_2 .

If addition schemes are not permitted, then the characterization of all obtainable spectra becomes more difficult. The questions are most naturally posed using notions such as the set of reachable states of the underlying bilinear systems ([4]).

8 From data to spectral parameters

Find a state space realization, i.e. (A_k, b_k, c_k) s.t.:

$$fid(n\Delta T) \approx c_k A_k^{n-1} b_k, \quad n=1,2,\ldots,$$

where ΔT is the sampling interval (see e.g. [3],[1],[6]).

$$TA_kT^{-1} =: diag(\alpha_1, \ldots, \alpha_k) =: dA_k,$$

Then with
$$dB_k := Tb_k$$
, $dC_k := C_k T^{-1}$,

$$fid(n) \approx dC_k dA_k^{n-1} dB_k = \sum_{i=1}^k \gamma_i \beta_i \alpha_i^{n-1}, \quad n = 1, 2, \dots,$$

where
$$dB_k = (\beta_1 \cdots \beta_k)^T$$
, $dC_k = (\gamma_1, \cdots, \gamma_k)$.

As
$$lpha_jpprox e^{(2\pi i\omega_j-d_j)\Delta T}, \quad j=1,2,\ldots,k,$$
 the frequency estimates are

$$\hat{\omega}_j = \frac{angle(\alpha_j)}{2\pi\Delta T}, \quad j = 1, 2, \dots, k,$$

the estimates of the damping factors are

$$\hat{d}_j = \frac{-log|\alpha_j|}{\Delta T}, \quad j = 1, 2, \dots, k.$$

For two-dimensional data a similar approach can be carried out using realization algorithms for two-dimensional systems ([5]).

9 Data processing

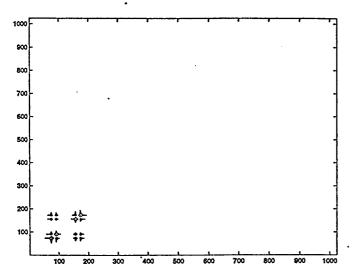
Algorithms were tested that are based on the above formulation of NMR experiments using simulated data of a COSY type spectrum of a coupled two spin system (Figure 1 and 2). The simulations were carried out first with noise free data and then with noisy data (Figures 1-12). To test how well the proposed methods can extend short data sets the original noise free data set was reduced to the subset of its first 16 by 16 data points. Figures 3 and 4 show the spectrum that is obtained after zero-filling this data set. The 16 multiplet structure of the spectrum is no longer resolved. This 16 by 16 data set was then extended to a 1024 by 1024 data set. The by it oasts set was tien extended to a 1024 by 1024 of a data set. The spectrum (Figures 5 and 6) was compared with the spectrum of the actual full data set. The errors between the extended data and the actual data was less than 10⁻⁸ which indicates that for practical purposes the extensions provide perfect reconstructions of the actual data in the noise free case. The estimates of the spectral parameters were also essentially perfect up to machine precision.

precision.

The proposed methods are also designed to be able to deal with noisy data. To test this property a relatively high level of white noise was added to the simulated data (see Figure 7). Due to the high level of noise the extensions and parameter estimates for the of the by 16 data set were no longer reliable. However, for a 128 by 128 data set almost perfect noise suppression and data extension to the full data length could be achieved (Figure 8). For a 32 by to the full data length could be achieved (Figure 8). For a 32 by 32 data subset very good noise suppression and somewhat acceptable data reconstruction could be achieved (Figures 11 and 12). For the same 32 by 32 data set zero-filing provided unacceptable spectral resolution (Figures 9 and 10). The parameter estimates for the 128 by 128 data set produced very good parameter estimates with error of less than one percent (and significantly better depending on the precise implementation of the approach). As can be inferred from Figure 12 the accuracy of the parameter estimates for the 32 by 32 data set was less good but still acceptable considering the noise level.

References

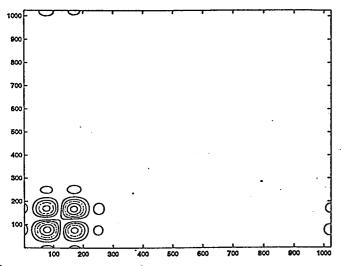
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2500 2500 1500 1000 2000 400 600 800 1000 120

Figure 1: Two dimensional spectrum of simulated noise free 1024 x 1024 data set (in absolute value mode).

Figure 2: One-dimensional slice of spectrum in Figure 1.



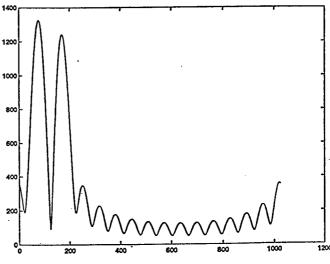
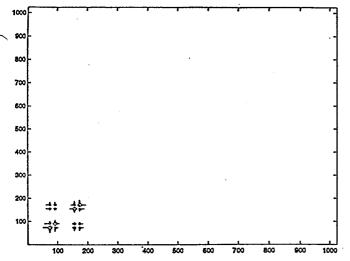


Figure 3:
Of the data set of Figure 1 the 16x16 subset of data points was retained that corresponds to the first 16 points in the t1 and t2 dimensions. This 16x16 dataset was then zero filled and Fourier transformed.

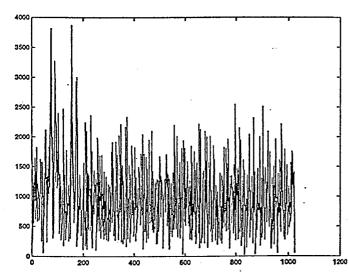
Figure 4: One-dimensional slice of spectrum in Figure 3. There is a clear loss of resolution in comparison to Figure 2.



3500 3500 2500 1500 1000 500 200 400 600 800 1000 1200

Figure 5:
The same 16x16 subset of the data set as in Figure 3 was extended to a 1024x1024 data set using Method 1 as described in the proposal. The resulting extended data set was then Fourier transformed. A numerical comparison between this spectrum and the spectrum of the full data set in Figure 1 shows indicates that the spectra are essentially identical up to round off errors.

Figure 6:
One dimensional slice of spectrum in Figure 5.
It demonstrates that the proposed method has recovered the resolution of the original simulated data in stark contrast to zero filling as can be seen in comparison with Figure 4.



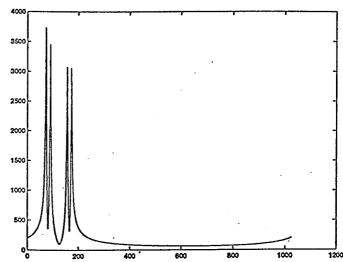


Figure 7: One dimensional slice of the spectrum of the same data as in Figures 1 and 2, but with white noise added to the time domain data.

Figure 8:
The noisy data set of Figure 7 has been reduced to a 128x128 data set. This figure shows the same slice of the spectrum as in Figures 2 and 7 after processing with Method 1. There is essentially no difference to the noise free and full data case of Figure 2.

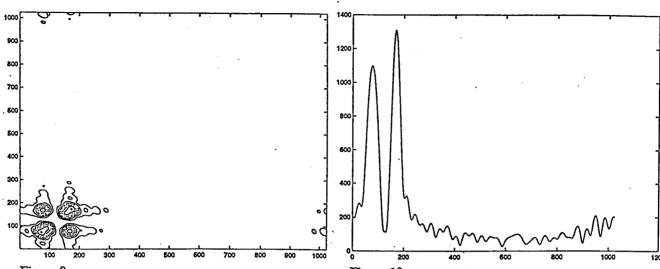


Figure 9: Figure 10: One dimensional slice of spectrum of Figure 9. filled. The resulting spectrum does not resolve the multiplet structure.

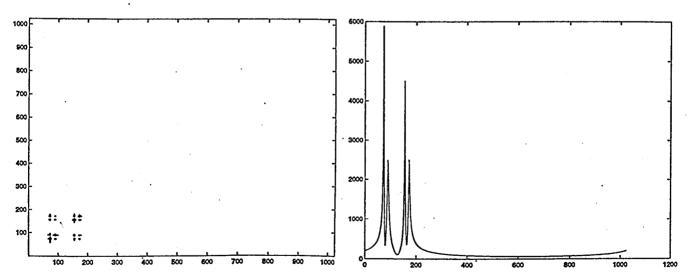


Figure 11:
Two dimensional spectrum after noisy 32 by 32 data set has been noise reduced and extended using Method 1.
In contrast to zero filling (Figure 9) the multiplet structure is fully resolved.

Figure 12:
One dimensional slice of spectrum in Figure 11.
Clearly the noise reduction was successful. However, in contrast to the noise free case of Figure 6 and the case of the larger noisy data set of Figure 8 some perturbations of the spectrum are introduced. Nevertheless, unlike processing solely based on zero-filling (Figure 10) the method could recover the essential features of the spectrum.